IN THE CLAIMS:

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- 1. (Currently Amended) A manipulator-guided gripping device (1) for workpieces [[,]] and especially body parts in [[the]] a body shell, wherein the gripping device (1) has comprising: a plurality of said device parts (6, 7, 8) and; a safety means (9) for detecting changes in geometry, characterized in that the safety means (9) has including at least one deflectable safety device (10) at the device parts (6, 7, 8).
- 2. (Currently Amended) A gripping device in accordance with claim 1, characterized in that wherein the deflectable safety device (10) is arranged at a junction point (23) between the device parts (6, 7, 7', 7", 8).
- 3. (Currently Amended) A gripping device in accordance with claim 1 or 2, characterized in that wherein the deflectable safety device (10) has at least two said safety device parts (11, 12) that are mounted such that they can deflect along one or more axes in case of overload.
- 4. (Currently Amended) A gripping device in accordance with claim 1, 2 or 3, characterized in that wherein the safety device parts (11, 12) are connected to one another by clamping connection and frictional connection.
 - 5. (Currently Amended) A gripping device in accordance with claim 1, 2 or 3,

characterized in that wherein the safety device parts (11, 12) are connected to one another in a positive-locking manner by at least one said deflectable locking element (13).

- 6. (Currently Amended) A gripping device in accordance with one of the above claims claim 3, characterized in that wherein the safety device parts (11, 12) are connected to a device part (6, 7, 7', 7'', 8) each.
- 7. (Currently Amended) A gripping device in accordance with one of the above claims claim 5, characterized in that wherein the locking element (13) is arranged between the safety device parts (11, 12).
- 8. (Currently Amended) A gripping device in accordance with one of the above claims claim 5, characterized in that wherein the locking element (13) is held with an elastic clamping element (20).
- 9. (Currently Amended) A gripping device in accordance with one of the above claims claim 8, characterized in that wherein the locking element (13) and the clamping element (20) are set to a force that holds the safety device parts (11, 12) during normal operation.
- 10. (Currently Amended) A gripping device in accordance with one of the above claims claim 1, characterized in that wherein the safety device parts (11, 12) are designed as a sphere

(15, 15') and as a socket (14, 14') surrounding same.

- 11. (Currently Amended) A gripping device in accordance with one of the above claims claim 10, characterized in that wherein the sphere is designed as a joint ball (15) and the socket is designed as a straight tube section (14).
- 12. (Currently Amended) A gripping device in accordance with one of the above claims claim 10, characterized in that wherein the sphere is designed as a ring-shaped collar (15') with a spherical outer side and the socket is designed as a calotte (14') surrounding same with an inner side rounded in a complementary manner.
- 13. (Currently Amended) A gripping device in accordance with claim 12, characterized in that wherein the collar (15') and the calotte (14') surrounding same have essentially the same width.
- 14. (Currently Amended) A gripping device in accordance with claim 3 one of the claims 1 through 9, characterized in that wherein the safety device parts (11, 12) are designed as said disk mounts (16, 17) with parallel working surfaces.
- 15. (Currently Amended) A gripping device in accordance with one of the above claims claim 3, characterized in that wherein the safety device parts (11, 12) have an adjusting means

(33) for reproducible mutual positioning.

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16. (Currently Amended) A gripping device in accordance with one of the above claims claim 3, characterized in that wherein the safety device parts (11, 12) have one or more said detectors (24), which detect and signal deflections of the safety device parts (11, 12).

17. (Currently Amended) A gripping device in accordance with one of the above claims claim 16, characterized in that wherein the detector (24) is arranged eccentrically in relation to the central axis (38) of the safety device parts (11, 12).

18. (Currently Amended) A gripping device in accordance with claim 16 one of the claims 1 through 16, characterized in that wherein the detector (24) is arranged centrally in the central axis (38) of the safety device parts (11, 12) the safety device parts have an adjusting means for reproducible mutual positioning and the detector is designed as a part of the adjusting means (33).

19. (Currently Amended) A gripping Deflectable safety device in accordance with claim 18, characterized in that wherein the detector (24) has a pressure piece (44), which is mounted in an elastically movable manner in an end-side tube section (43) of the shaft (37) and whose said projecting head part (45) engages a mount (47) at a projection (39) of the other safety device part (11) in a positive-locking manner, wherein a microswitch (48) is arranged at the

contact point.

- 20. (Currently Amended) A gripping device in accordance with one of the above claims claim 16, characterized in that wherein the detectors (24) are connected to a process control (26).
- 21. (Currently Amended) A gripping device in accordance with one of the above claims claim 1, characterized in that the gripping device (1) has further comprising; a frame (4) with one or more said gripping or clamping elements (6) and with a docking point (5) for connection to a mechanical manipulator (2), especially in the form of a multiaxial industrial robot.
- 22. (Currently Amended) A gripping device in accordance with one of the above claims claim 1, characterized in that wherein the frame (4) has a plurality of said frame tubes (7, 8).
- 23. (Currently Amended) A gripping device in accordance with claim 15, characterized in that wherein the frame tubes (7, 8) are divided, and wherein a deflectable safety device (10) is arranged between the tube sections (7', 7").